

Ministry of Education and Science of the Russian Federation
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Control Systems and Technology Department

Course Final Project Report

Shakey's World
Discipline: History and Methodology of Informatics and Computer Engineering
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Course Project: Shakey's World History and Methodology of Informatics

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Summary

A program, built in Java, is called "Shakey's World". In this world, there is a robot that can roam around in a digital environment. This robot can open/close doors, push a box around, climb on/off a box, and turn lights on/off.

There are 4 rooms, 1 hallway, 1 robot, and one box. Each room has a door, light switch, and light fixture.

Program Usage

The world of Shakey includes both manual and automatic methods to move Shakey around the environment.

Below is a list of commands, and their description.

Shakey's World - X Hallway 4

Manual Controls

Keyboard Key	Description
$\uparrow \downarrow \leftarrow \rightarrow$	Move shakey around the room.
d	Open or close a door.
С	Climb up/down from box, if near a box.
1	Turn on a light, if on the box near the light switch.

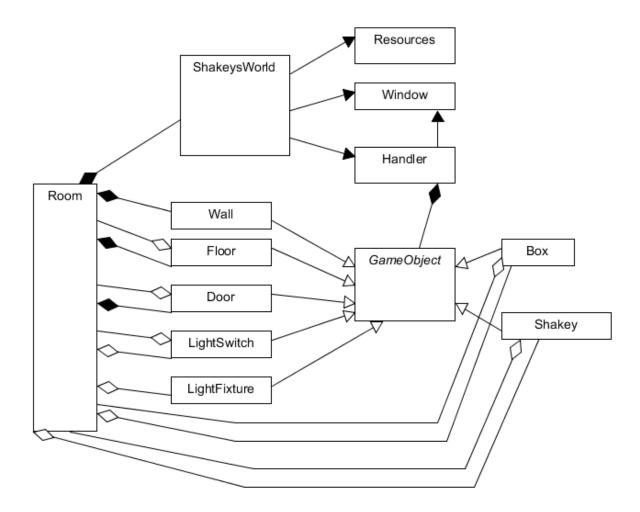
Automatic Controls

Keyboard Key	Description
1234	Go to specified room, if in hallway.
h	Go to hallway.
S	1. Move the box to the light switch
	2. Climb on the box.
	3. Switch the light on/off.

Classes

Below is a layout of the classes contained in the "ShakeysWorld" program. In the next sections, each individual area is discussed in more detail.

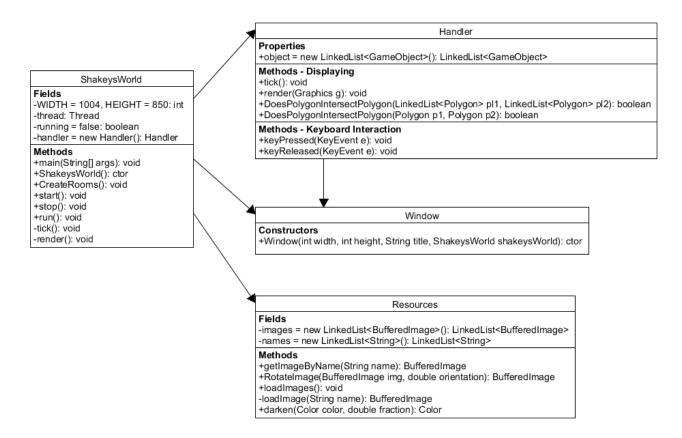
- 1.) The **ShakeysWorld** class starts the program and creates the environment.
- 2.) All objects in the environment are inherited from the abstract <u>GameObject</u> class. (examples: Wall, Floor, Shakey, Box)
- 3.) The Room class is used as an organization tool to create the environment for shakey.
- 4.) The <u>Handler</u> handles keyboard events, repositions objects, and renders content to the <u>Window</u>.



Display Engine

The main application is the class "ShakeysWorld". This class calls the following 3 important classes.

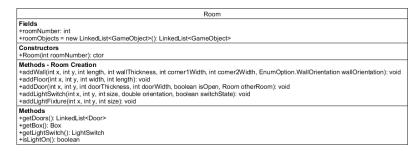
- 1. Handler Handles all GameObject updates.
 - a. Checks for collision detection between objects.
 - b. Updates all object positions.
 - c. Displays the results using the Window class.
 - d. Handles keyboard input.
- 2. Window Displays the results to the screen.
- 3. **Resources** Handles commonly used code and access to the image files.

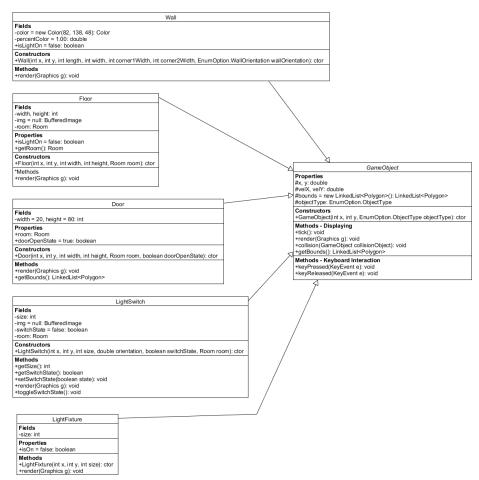


Environment - Rooms

A room is composed of various objects. Each of these objects is inherited by the "GameObject" class.

- 1. Wall The boundaries for each room
- 2. Floor The background of the room.
- 3. **Door** An object that can prevent or allow access to the room.
- 4. LightSwitch Changes the lighting state of the room.
- 5. **LightFixture** Represents the lighting of the room.
- 6. **GameObject** The abstract base class for all objects.

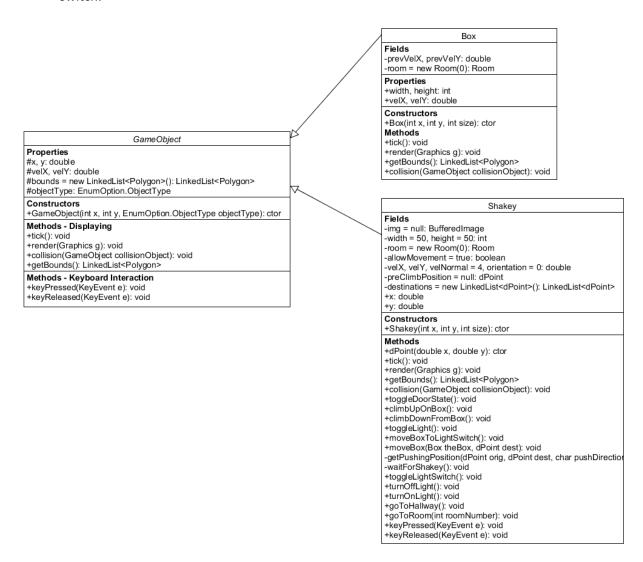




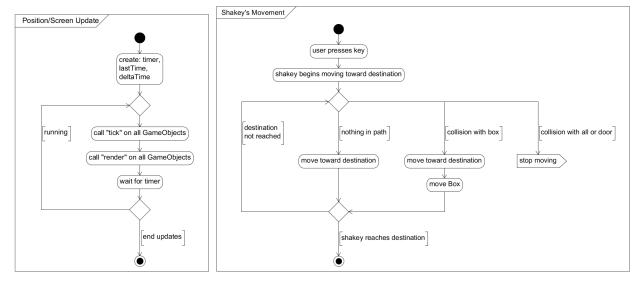
Shakey and Box

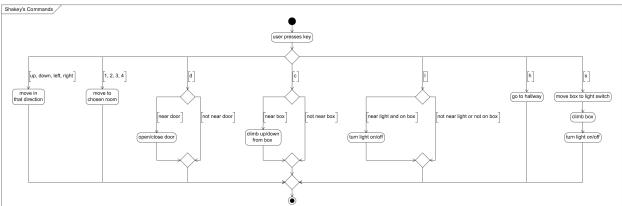
The two most important objects in the program are Shakey and the Box.

- 1. Shakey a robot that can be manually or automatically moved around the rooms.
- 2. **Box** an object that shakey can push around the rooms. The box is used to reach the light switch.

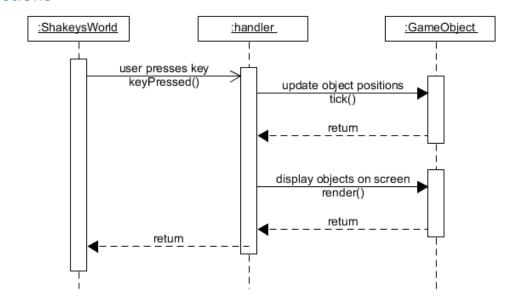


Activities

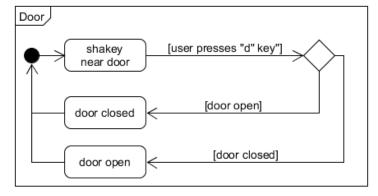


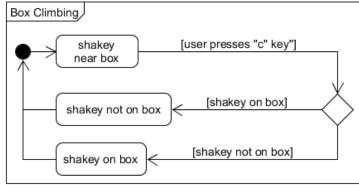


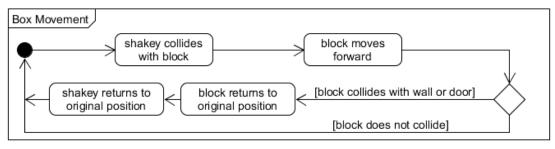
Interactions

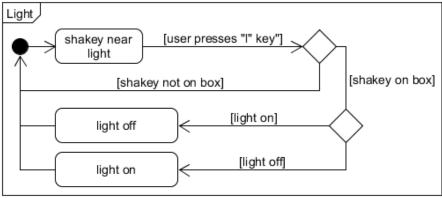


States









Components

